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On composite lacunary polynomials and the proof of a conjecture of Schinzel

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Abstract. Let g(x) be a fixed non-constant complex polynomial. It was conjectured by Schinzel that if g(h(x)) has boundedly many terms, then $h(x) \in \mathbb{C}[x]$ must also have boundedly many terms. Solving an older conjecture raised by Rényi and by Erdös, Schinzel had proved this in the special cases $g(x) = x^d$; however that method does not extend to the general case. Here we prove the full Schinzel's conjecture (actually in sharper form) by a completely different method. Simultaneously we establish an "algorithmic" parametric description of the general decomposition f(x) = g(h(x)), where f is a polynomial with a given number of terms and g, h are arbitrary polynomials. As a corollary, this implies for instance that a polynomial with l terms and given coefficients is non-trivially decomposable if and only if the degree-vector lies in the union of certain finitely many subgroups of \mathbb{Z}^l .

INTRODUCTION. The behaviour of (complex) polynomials under the operation of composition has been studied by several authors, starting with J.F. Ritt (see [S2] for an account of the theory). Here we deal with this aspect when some of the involved polynomials are *lacunary* (also called *sparse*), i.e. the number of their terms is viewed as fixed, while the corresponding degrees (and coefficients) may vary. So, we write $f(x) = a_1 x^{m_1} + \ldots + a_l x^{m_l}$ for a lacunary polynomial with (at most) l terms and we study its *decomposability*, i.e. the equation f(x) = g(h(x)), with $g, h \in \mathbb{C}[x]$ of degree > 1; both decomposable and lacunary polynomials have played a special role in several (algebraical and arithmetical) investigations (see e.g. [S2]).

A trivial case occurs when $h(x) = ax^n + b$; now, f is of the shape $g \circ h$ if and only if n divides all the degrees of the terms which occur in f(x). For non-trivial decompositions, in a recent paper we established a bound (which will be useful later) for the degree of g(x) (see Thm. 1 of [Z]):

Theorem A. ([Z], Thm. 1) Suppose that $g, h \in \mathbb{C}[x]$ are non-constant, that h(x) is not of the shape $ax^n + b$ and that g(h(x)) has at most l terms. Then $\deg g \leq 2l(l+1)$.

This somewhat controls the polynomial g(x). To control h(x) leads to subtler problems already in basic cases, like $g(x) = x^2$: it was conjectured by Rényi and independently by Erdös in 1949 [E] that a bound for the number of terms of $h(x)^2$ implies a bound for the number of terms of h(x). In 1987 Schinzel [S] found an ingenious proof of this conjecture, actually for all powers $h(x)^d$ (and he gave explicit bounds). He went on to conjecture that for a fixed non-constant $g \in \mathbb{C}[x]$ such that g(h(x)) has at most l terms, the number of terms of h(x) is bounded by a function only of l. (This generalized conjecture, as we shall see, has significant implications in the whole context.) He also remarked that his method for the powers $h(x)^d$ was insufficient for a general proof.

In this paper we fully prove this conjecture of Schinzel, actually in sharper form, namely without fixing the polynomial g(x). We have:

Theorem 1. There exists a (computable) function B on \mathbb{N} such that if $g, h \in \mathbb{C}[x]$ are non-constant polynomials and if g(h(x)) has at most l terms, then h(x) has at most B(l) terms.

Our arguments follow a completely different path with respect to Schinzel's proof of the special case (so in particular they provide an alternative proof of the Rényi-Erdös conjecture). They mainly rely on a kind of modified Puiseux expansions and on a lower bound for approximations by sums of S-units in function fields (see Prop. 1 below); this may be viewed as a case of Schmidt Subspace Theorem in function fields.

The present proofs would easily yield an explicit, though very large, estimation for B(l), but for simplicity we do not calculate it here. (1)

Theorem 1 in full generality represents (together with Theorem A) an indispensable tool to obtain the classification of polynomials f(x), with at most l terms, which are "decomposable", i.e., of the shape g(h(x)) with g,h of degree > 1. Simultaneously with Theorem 1 we establish a complete "algorithmic" description in finite terms. That is, for any fixed l we give an effective procedure to write down a finite number of parametrizations for all the equations $f(x) = a_1 x^{m_1} + \ldots + a_l x^{m_l} = g(h(x))$ where by "parametrization" we roughly mean:

"algebraic variety for the coefficients-vector + integer lattice for the degrees-vector".

We can rephrase this by saying that we can obtain all the equations in question from finitely many "generic equations" just by substitution. More precisely we have:

Theorem 2. Let l be a positive integer. There exist an integer p, finitely many affine varieties V_j/\mathbb{Q} , $j=1,\ldots,J$, and polynomials $F_j,H_j\in\mathbb{Q}[\mathcal{V}_j][z_1^{\pm 1},\ldots,z_p^{\pm 1}]$, $G_j\in\mathbb{Q}[\mathcal{V}_j][z]$, such that:

- (i) $F_j = G_j \circ H_j$.
- (ii) F_j has at most l terms as a Laurent polynomial in z_1, \ldots, z_p and $\deg_z G_j \leq 2l(l+1)$.
- (iii) If $f, g, h \in \mathbb{C}[x]$ are such that $f = g \circ h$, $h(x) \neq ax^n + b$ and f has at most l terms, then, for some j there exist a point $P \in \mathcal{V}_j(\mathbb{C})$ and integers u_1, \ldots, u_p such that $f(x) = F_j(P, x^{u_1}, \ldots, x^{u_p})$, $g(x) = G_j(P, x)$, $h(x) = H_j(P, x^{u_1}, \ldots, x^{u_p})$.

Finally, one may effectively find p, J, equations for the \mathcal{V}_i and expressions for the F_i, G_i, H_i .

See also the equivalent Theorem 2* below for an alternative formulation.

Theorem 2 follows rather easily from Theorems A, 1. However the proof of Theorem 1 in turn involves a description like in Theorem 2, so in fact the proofs will appear at the same time.

We also note that Theorem 2 immediately implies for instance the following:

Corollary. For $a_1, \ldots, a_l \in \mathbb{C}$, there exists a finite union $M = M(a_1, \ldots, a_l)$ of subgroups of \mathbb{Z}^l such that $a_1 x^{m_1} + \ldots + a_l x^{m_l} \in \mathbb{C}[x]$ is nontrivially decomposable if and only if $(m_1, \ldots, m_l) \in M$.

We can also add that if $\mathbb{Q}(a_1,\ldots,a_l)$ is finitely presented the finitely many relevant subgroups are computable. Moreover, a similar corollary holds concerning the decomposability of $a_1x^{m_1} + \ldots + a_lx^{m_l}$ for some (a_1,\ldots,a_l) running through a given algebraic variety.

⁽¹⁾ Schinzel [S] produces explicit bounds for the special cases $g(x) = x^d$; we believe that the present method leads to weaker bounds in those cases. For bounds in the opposite direction see [E], [S2].

Some of the arguments should extend to Laurent polynomials (as in [Z]), to rational functions and also to equations of the form $g(c_1x^{m_1},\ldots,c_lx^{m_l},h(x))=0$, for a fixed $g\in\mathbb{C}[X_1,\ldots,X_l,Y]$, where $c_i\in\mathbb{C}$, $m_i\in\mathbb{N}$ and where h(x) is a polynomial. In turn, this is related to a Bertini-type theorem, for the irreducibility of the intersection of a subvariety of \mathbb{G}_m^n with families of algebraic subgroups or cosets. Also in view of the fact that this topic falls somewhat far from the present one, we do not treat it here.

PROOFS. We shall need a version of the Voloch and Brownawell & Masser "S-unit equation theorem for function fields". Actually, rather than S-unit equations we shall meet approximations by S-units, and for our purposes the following variant shall be useful, modelled on [Z2, Thm. 1]:

Proposition 1. Let K/\mathbb{C} be a function field in one variable, of genus g, and let $\varphi_1, \ldots, \varphi_n \in K$ be linearly independent over \mathbb{C} . Let S be a finite set of places of K containing all the poles of $\varphi_1, \ldots, \varphi_n$ and also all the zeros of $\varphi_1, \ldots, \varphi_r$. Further, put $\sigma = \sum_{i=1}^n \varphi_i$. Then

$$\sum_{v \in S} (v(\sigma) - \min_{i=1}^{n} v(\varphi_i)) \le \binom{n}{2} (\#S + 2g - 2) + \sum_{i=r+1}^{n} \deg(\varphi_i).$$

Proof. Following [BM] and [Z2], for a non-constant $t \in K$ and $\varphi_1, \ldots, \varphi_n \in K$, we consider the Wronskian $W_t(\varphi_1, \ldots, \varphi_n)$, i.e. the determinant of the $n \times n$ matrix whose j-th row-entries are the (j-1)-th derivatives of the φ_i 's with respect to t. Since the φ_i are linearly independent over \mathbb{C} , we have $W_t \neq 0$ by a well-known criterion. Let $z \in K$ be another non-constant element. Then we have the known, easily proved, formula $W_z(\varphi_1, \ldots, \varphi_n) = \left(\frac{dt}{dz}\right)^{\binom{n}{2}} W_t(\varphi_1, \ldots, \varphi_n)$. For a place v of K we choose once and for all a local parameter t_v at v and we define $W_v := W_{t_v}$. This depends on the choice of t_v , but the formula shows that the order $v(W_v)$ depends only on v.

Since $W_t \in K^*$, the formula also shows that $\sum_v v(W_v) = \binom{n}{2} \sum_v (\mathrm{d}t/\mathrm{d}t_v) = \binom{n}{2} (2g-2)$. For $v \notin S$ we have $v(\varphi_i) \geq 0$ for $i=1,\ldots,n$, so $v(\mathrm{d}^m\varphi_i/\mathrm{d}t_v^m) \geq 0$ for all i,m and $v(W_v) \geq 0$. For $v \in S$, let $j=j_v$ be an index such that $v(\varphi_j) = \min_{i=1}^n (v(\varphi_i))$ and set $g_i = \varphi_i$ if $i \neq j$, $g_j = \sigma$. We have $W_v = W_v(g_1,\ldots,g_n)$. Also, $v(\mathrm{d}^mg_i/\mathrm{d}t_v^m) \geq v(g_i) - m$ for $m \geq 0$, whence

$$v(W_v) \ge \sum_{i=1}^n v(g_i) - \binom{n}{2} = v(\sigma) - v(\varphi_{j_v}) + \sum_{i=1}^n v(\varphi_i) - \binom{n}{2}.$$

Recalling that $v(\varphi_{j_v}) = \min_{i=1}^n v(\varphi_i)$ we then obtain

$$\binom{n}{2}(2g-2) = \sum_{v} v(W_v) \ge \sum_{v \in S} (v(\sigma) - \min_{i=1}^n v(\varphi_i)) + \sum_{i=1}^n (\sum_{v \in S} v(\varphi_i)) - \binom{n}{2} \#S.$$

Finally, for $i \leq r$ all zeros and poles of φ_i are contained in S so $\sum_{v \in S} v(\varphi_i) = 0$ for $i \leq r$. For i > r at least the poles of φ_i are contained in S, so $\sum_{v \in S} v(\varphi_i) \geq -\deg(\varphi_i)$ for i > r. Inserting this in the last displayed inequality yields the sought result.

The proof of Theorem 1 is based on two simple, though crucial, points. The first one is embodied in the proof of the following statement, which is actually a weak form of Theorem 1.

Proposition 2. There exists a (computable) function B_1 on \mathbb{N} such that if $g, h \in \mathbb{C}[x]$ are non-constant polynomials and if g(h(x)) has at most l terms, then h(x) may be written as a ratio of two polynomials having each at most $B_1(l)$ terms.

Proof. It plainly suffices to construct the function B_1 assuming that h(x) is not of the shape $ax^n + b$. Then, putting $d := \deg g$ and $m := \deg f$, d is a divisor of m, $\deg h = m/d$ and by Theorem A we have $d \le 2l(l+1)$.

For l=1 we may take $B_1(1)=2$: in fact, if g(h(x)) is a monomial ax^m , then g cannot have two distinct roots and must be therefore of the shape $b(x-\xi)^n$. Then $h(x)=\xi+\eta x^{m/n}$ $(b\eta^n=a)$ has at most two terms.

We now argue by induction, supposing that B_1 has been suitably defined on $\{1, \ldots, l\}$.

We write y = 1/x and $f(x) = ax^m(1 + b_1y^{n_1} + \ldots + b_ly^{n_l}) = ax^m\tilde{f}(y)$, say, where $n_0 := 0 < n_1 < \ldots < n_l \le m$. We may suppose that f has exactly l + 1 terms, so $ab_1 \cdots b_l \ne 0$.

From the equation g(h) = f we may write the Puiseux expansion for h = h(x) at $x = f = \infty$:

$$h(x) = c_{-1}f(x)^{1/d} + c_0 + c_1f(x)^{-1/d} + \dots, \qquad c_{-1}, c_0, c_1, \dots \in \mathbb{C},$$
(1)

for a suitable choice of the d-th root $f(x)^{1/d}$, where the c_j depend only on g; this identity is valid in $\mathbb{C}((y))$. We expand the various powers of this d-th root as $f(x)^{s/d} = a^{s/d}x^{ms/d}(1+b_1y^{n_1}+\ldots+b_ly^{n_l})^{s/d}$, using the multinomial theorem for the sum on the right:

$$\tilde{f}(y)^{s/d} = (1 + b_1 y^{n_1} + \dots + b_l y^{n_l})^{s/d} = \sum_{h_1, \dots, h_l} c_{s,d,\mathbf{h}} b_1^{h_1} \cdots b_l^{h_l} y^{h_1 n_1 + \dots + h_l n_l}, \tag{2}$$

where $\mathbf{h} := (h_1, \dots, h_l)$ runs through \mathbb{N}^l and where the $c_{s,d,\mathbf{h}}$ are certain universal coefficients.

Factoring g(x) we see that, since $x^{m-n_l}||f(x)=g(h(x))$, there exists a root ξ of g, of multiplicity $d_0 \leq d$, such that $x^{m-n_l}||(h(x)-\xi)^{d_0}$. Let us then write $\tilde{h}(y)=x^{-m/d}(h(x)-\xi)\in\mathbb{C}[y]$. It will suffice to prove the conclusion for \tilde{h} in place of h.

We have deg $\tilde{h} = \frac{m}{d} - \frac{m-n_l}{d_0} \leq \frac{n_l}{d}$ (since $d_0 \leq d$ and $n_l \leq m$). Also, subtracting ξ from both sides of (1) and dividing by $x^{m/d}$ we obtain, in the ring $\mathbb{C}[[y]]$, for certain $\gamma_{-1}, \gamma_0, \gamma_1, \ldots \in \mathbb{C}$,

$$\tilde{h}(y) = \gamma_{-1}\tilde{f}(y)^{1/d} + \gamma_0 y^{m/d} + \gamma_1 y^{2m/d} \tilde{f}(y)^{-1/d} + \dots,$$
(3)

We note that since $\tilde{h}(y)$ is a polynomial of degree $\leq n_l/d$, formula (3) shows that it is the sum of the terms on the right of (2), with s=1, for which $h_1n_1+\ldots+h_ln_l\leq n_l/d$, plus possibly $\gamma_0 y^{m/d}$. The number of such terms is $\ll (n_l/n_1)^l$, hence, if we knew that $n_1 > \epsilon_l n_l$ for some fixed $\epsilon_l > 0$ we could easily establish the conclusion of Theorem 1. This lower bound for n_1 isn't of course guaranteed, but nevertheless we shall show that we can somewhat reduce to this case.

We fix an integer $p, 0 \le p \le l-1$, and we write $\delta_p(y) = 1 + b_1 y^{n_1} + \ldots + b_p y^{n_p}$ (so $\delta_0(y) = 1$). Our main task will be now to establish that: if n_{p+1} is not much smaller than n_l (i.e. $\gg_l n_l$), then either we obtain the sought representation or n_p is as well not much smaller than n_l . We shall then conclude by backward induction on $p = l-1, l-2, \ldots$

To take advantage of the fact that n_{p+1} may be possibly "large" we expand $\tilde{f}(y)^{s/d}$ in a slightly different way, namely writing

$$\tilde{f}(y)^{s/d} = \delta_p(y)^{s/d} \left(1 + \frac{b_{p+1}y^{n_{p+1}} + \ldots + b_ly^{n_l}}{\delta_p(y)} \right)^{s/d}$$

and using the multinomial theorem for the root of the sum on the right. In this way each of the summands $\gamma_s y^{(1-s)m/d} \tilde{f}(y)^{s/d}$, $s = -1, 0, 1, \ldots$, on the right side of (3) will be expressed (again in the ring $\mathbb{C}[[y]]$) as an infinite sum of terms of the shape

$$c\delta_p(y)^{\frac{s}{d}-k}y^{\frac{(1-s)m}{d}+h_1n_{p+1}+\ldots+h_{l-p}n_l}, \qquad h_1+\ldots+h_{l-p}=k, \quad c\in\mathbb{C},$$
 (4)

for varying integers $h_1, \ldots, h_{l-p} \in \mathbb{N}$ and suitable constants $c = c(h_1, \ldots, h_{l-p}, s)$. Therefore $\tilde{h}(y)$ will be likewise expressed: note in fact that $\delta_p(y)^{1/d} \in \mathbb{C}[[y]]^*$ and that the infinite sum converges in $\mathbb{C}[[y]]$ since $(1-s)m/d \to +\infty$ as $s \to -\infty$.

We now consider all the terms of the shape (4) such that the exponent of y is $\leq 2n_l$, i.e. $\frac{(1-s)m}{d} + h_1 n_{p+1} + \ldots + h_{l-p} n_l \leq 2n_l$. Clearly for this we must have $s \geq 1 - 2d$ and $\max h_i \leq 2n_l/n_{p+1}$. Hence the number L of such terms is bounded by a certain function of d and of n_l/n_{p+1} : for our present purposes we may take for instance the rough estimate $L \leq (2d+1)(1+(2n_l/n_{p+1}))^l$.

Denoting by t_1, \ldots, t_L such terms, we have in the ring $\mathbb{C}[[y]]$,

$$\tilde{h}(y) = t_1 + \ldots + t_L + O(y^{2n_l}).$$
 (5)

If t_1, \ldots, t_L are linearly dependent over \mathbb{C} , we may use a linear relation to replace some t_i by a linear combination of the others. Hence, replacing L with a possibly smaller number and changing if necessary the t_i with suitable constant multiples of themselves, we may assume that the t_i in (5) are linearly independent over \mathbb{C} and that they are still of the shape (4).

With the purpose of applying Proposition 1, we proceed to define the relevant objects which appear in that statement. We define K as the function field $\mathbb{C}(y, \delta_p(y)^{1/d})$. We readily find $2g - 2 \leq dn_p$ for the genus. We let n = L + 1, $\varphi_i := -t_i$ for $i = 1, \ldots, L$, $\varphi_{L+1} := \tilde{h}(y)$, so in fact $\varphi_i \in K$ for all i. Also, $\sigma = \tilde{h}(y) - t_1 - \ldots - t_L$. We further let r = L and we define S as the set of zeros/poles of $\varphi_1, \ldots, \varphi_L$ together with the poles of φ_{L+1} . Now, from (4) we see that $\varphi_1, \ldots, \varphi_L$ have zeros/poles at most at the places of K above 0 or ∞ of $\mathbb{C}(y)$ or above the roots of $\delta_p(y)$, while $\varphi_{L+1} = \tilde{h}(y)$ has a pole only at the places of K above ∞ . This gives at most $d(2 + n_p)$ places in S.

We now distinguish between two alternatives.

First case. This occurs when $\varphi_1, \ldots, \varphi_n$ are linearly dependent over \mathbb{C} . In a relation of linear dependence φ_{L+1} must appear because we are assuming that $\varphi_1, \ldots, \varphi_L$ are independent. Then we may express $\varphi_{L+1} = \tilde{h}(y)$ as a linear combination of at most L terms of the shape (4). Let $e := [K : \mathbb{C}(y)]$, so e is a certain divisor of d, in fact the least integer such that $\delta_p(y)^e$ is a d-th power in $\mathbb{C}(y)$.⁽²⁾ We may then write the said linear relation as

$$\tilde{h}(y) = \sum_{j=0}^{e-1} \delta_p(y)^{j/d} \Lambda_j,$$

where $\delta_p(y)^{j/d}\Lambda_s$ is the sum of the terms of the shape (4) in the linear relation, for which $s \equiv j \pmod{e}$; in particular, $\Lambda_j \in \mathbb{C}(y)$. We deduce that $\tilde{h}(y) = \Lambda_0$.

⁽²⁾ In fact we must have e = 1 in this case, but we won't need this.

Note that $\delta_p(y)^{e/d}$ is a certain polynomial $\eta_p(y)$ such that $\eta_p(y)^{d/e} = \delta_p(y)$ has at most $p+1 \leq l$ terms. By the inductive assumption $\eta_p(y)$ can be written as a ratio of two polynomials with at most $B_1(l)$ terms. Also, Λ_0 is a sum of at most L terms of the shape

$$c\eta_p(y)^{\frac{s-kd}{e}}y^{\frac{(1-s)m}{d}+h_1n_{p+1}+\ldots+h_{l-p}n_l}, \qquad e|(s,d), \quad |s| \leq 2d-1, \quad \max(h_i) \leq 2n_l/n_{p+1}.$$

In particular, since $k = \sum h_i \leq 2ln_l/n_{p+1}$, since $d \leq 2l(l+1)$ and since $L \leq (2d+1)(1+(n_l/n_{p+1}))^l$, $\tilde{h}(y) = \Lambda_0$ may be written as a ratio of two polynomials each with $\leq B_2(l, n_l/n_{p+1})$ terms, where $B_2(l, u)$ is a function which may be easily estimated in terms of $B_1(l)$ and of $u \geq 1$.

Second case. Let us now analyze the remaining possibility, i.e. that $\varphi_1, \ldots, \varphi_n$ are linearly independent over \mathbb{C} . In this case the conclusion of Proposition 1 holds.

The meaning of (5) is that $v_0(\sigma) \geq 2n_l v_0(y) \geq 2n_l$ for some place v_0 of K above the zero of $\mathbb{C}(y)$, so $v_0 \in S$. We clearly have $\min_{i=1}^n v_0(\varphi_i) \leq v_0(\varphi_{L+1}) = 0$, because $\tilde{h}(0) \neq 0$.

Since $v(\sigma) \ge \min_{i=1}^n v(\varphi_i)$ for all places v of K and since $\deg_K \tilde{h}(y) \le d \deg \tilde{h} \le n_l$, Proposition 1 yields

$$2n_l \le {L+1 \choose 2} (\#S + dn_p) + n_l \le \frac{(L+1)^2}{2} (\#S + dn_p) + n_l.$$

We have seen that $\#S \leq d(2+n_p)$, hence this inequality becomes

$$n_l \le (L+1)^2 d(1+n_p) \le 16^{l+1} d^3 (n_l/n_{p+1})^{2l} (1+n_p),$$
 (6)

where we have used our previous estimate for L.

Now, suppose that the first alternative never occurs, for p = l - 1, l - 2, ..., 0. Then (6) is always true. For $p \ge 1$ it gives

$$(n_l/n_p) \le 16^{l+2} d^3 (n_l/n_{p+1})^{2l}.$$

Hence, since $n_l/n_{p+1} = 1$ for p = l - 1, we obtain by backward induction that n_l/n_1 is bounded in terms of l only (recall $d \leq 2l(l+1)$). We already noted that this suffices, but we may also apply (6) for p = 0 to get that n_l is bounded only in terms of l. Hence the degree of $\tilde{h}(y)$ and a fortiori the number of its terms are bounded by a (computable) function of l, and we are done.

Therefore we may assume that the first alternative sometimes occurs, and we denote by $q \ge 0$ the last such occurrence. Then for p > q the second alternative must hold, so we have (6) for p > q. As before, inductively we may use this to show that n_l/n_{q+1} is bounded by a function of l only. Also, since the first alternative occurs for p = q, the previous argument yields that $\tilde{h}(y)$ can be written as a ratio of two polynomials whose number of terms is bounded by $B_2(l, n_l/n_{q+1})$; but this is in turn bounded by a function only of l, concluding finally the proof of Proposition 2.

To deduce Theorem 1 from Proposition 2 we have only to show that h(x) is not just a "ratio of polynomials with boundedly many terms", but that itself has boundedly many terms; the examples $(x^n - 1)/(x - 1)$ show that this is not automatic. In our case, this will follow from a description equivalent to Theorem 2, which we state as:

Theorem 2*. Let l be a positive integer and write $f(x) = a_1 x^{m_1} + \ldots + a_l x^{m_l} = g(h(x)) \in \mathbb{C}[x]$, where deg g, deg h > 1 and where h(x) is not of the shape $ax^n + b$.

Then deg $g \le 2l(l+1)$ and h(x) has at most B = B(l) terms.

Further, there are finitely many algebraic varieties $V_j \subset \mathbb{A}^{l+2l(l+1)+1+B}$ (defined over \mathbb{Q}) and subgroups Λ_j of \mathbb{Z}^{l+B} , $j=1,\ldots,J=J(l)$, such that for some $j\in\{1,\ldots,J\}$ the vector of coefficients of f,g,h lies in V_j and the vector of exponents of x in f,h lies in Λ_j .

Conversely, if these vectors lie in V_i , Λ_i then the equation $f = g \circ h$ holds.

Finally, one may effectively find J, defining equations for the \mathcal{V}_j and generators for the Λ_j .

Proof of Theorems 1,2*. Let f(x) = g(h(x)) where f(x) has at most l terms and where h(x) is not of the shape $ax^n + b$. Then, from Theorem A and Proposition 2 it follows that $\deg g \leq 2l(l+1) =: \ell$ and that h(x) is a ratio $h_1(x)/h_2(x)$ where $h_1, h_2 \in \mathbb{C}[x]$ have each at most $B = B_1(l)$ terms. We may then write

$$f(x) = \sum_{i=1}^{l} a_i x^{m_i}, \quad g(x) = \sum_{i=0}^{\ell} b_j x^j, \quad h_r(x) = \sum_{k=1}^{B} c_{rk} x^{n_{rk}}, \quad r = 1, 2,$$

which yields

$$\left(\sum_{k=1}^{B} c_{2k} x^{n_{2k}}\right)^{\ell} \left(\sum_{i=1}^{l} a_{i} x^{m_{i}}\right) - \sum_{j=0}^{\ell} b_{j} \left(\sum_{k=1}^{B} c_{1k} x^{n_{1k}}\right)^{j} \left(\sum_{k=1}^{B} c_{2k} x^{n_{2k}}\right)^{\ell-j} = 0.$$

Expanding everything we obtain the vanishing of a sum of terms each of the shape γx^{μ} , where:

- (i) The occurring degrees μ are certain explicitly given linear combinations of m_i, n_{1k}, n_{2k} (i = 1, ..., l, k = 1, ..., B) with coefficients in \mathbb{N} , bounded by ℓ .
- (ii) The occurring coefficients γ are certain explicit monomials (over \mathbb{Q}) in the a_i, b_j, c_{1k}, c_{2k} (i = 1, ..., l, j = 1, ..., l, k = 1, ..., B), the set of these monomials depending only on l.

We now group together all the terms γx^{μ} having equal degree μ . This gives a partition of the terms, the possible partitions being finite in number.

For each such partition, the various equalities between the degrees gives (in view of (i)) a linear system with integral coefficients, among the m_i, n_{1k}, n_{2k} . Note that by (i) all the systems so obtained may be written down, and their number is bounded only in terms of l. Forgetting the fact that the m_i, n_{rk} are non-negative, each system admits a parametric solution of the shape

$$m_i = \sum_{j=1}^p \alpha_{ij} u_j, \quad n_{rk} = \sum_{j=1}^p \beta_{rkj} u_j, \quad r = 1, 2,$$
 (7)

with certain computable integers p, α_{ij} , β_{rkj} depending only on the linear system and bounded only in terms of l, where the u_j may take any integer values; that is, for arbitrary values of the u_j the degrees are equal in groups according to the partition (and conversely).

After grouping all the terms according to the partition, we equate to zero all the corresponding coefficients. This gives an algebraic system in the a_i, b_j, c_{1k}, c_{2k} , defining a certain affine algebraic variety (over \mathbb{Q} , possibly reducible). These equations have only finitely many possibilities which can be enumerated, and their number is bounded only in terms of l.

Plainly, each relevant equality f(x) = g(h(x)) produces then a point in one of these varieties and an integral solution of the corresponding linear system. (3)

Conversely, each point in a relevant variety together with an integer solution of the corresponding linear system gives an equality f(x) = g(h(x)), except for the fact that f, h may now be Laurent polynomials (that is, polynomials in x, x^{-1}). If we restrict to non-negative integer solutions we obtain polynomial equalities. (4)

Now comes the second main point of the proof of Theorem 1. Take any given equation f(x) = g(h(x)) of the shape in question. The coefficients of f, g, h_1, h_2 will then give a certain point P_0 in one of the above varieties. And the degrees in f, h_1, h_2 will give a solution \mathbf{w}_0 of the corresponding linear system, expressed by a parameter vector \mathbf{u}_0 as in (7). However, by construction, if we keep the point P_0 fixed and vary the solution \mathbf{w}_0 to any solution \mathbf{w} of the same system, given by the parameter \mathbf{u} , we shall obtain another equation $f^{\mathbf{u}}(x) = g(h_1^{\mathbf{u}}(x)/h_2^{\mathbf{u}}(x))$, with the same coefficients but generally different degrees.

Let us exploit what this means. The degrees occurring in $f^{\mathbf{u}}$ are certain fixed linear combinations of u_1, \ldots, u_p , with integer coefficients depending on the α_{ij} in (7), and an analogous fact holds for $h_1^{\mathbf{u}}, h_2^{\mathbf{u}}$. In other words, by (7) we can write

$$f^{\mathbf{u}}(x) = F(x^{u_1}, \dots, x^{u_p}), \qquad h_r^{\mathbf{u}}(x) = H_r(x^{u_1}, \dots, x^{u_p}), \qquad r = 1, 2,$$

for certain Laurent polynomials $F, H_1, H_2 \in \mathbb{C}[z_1^{\pm 1}, \dots, z_p^{\pm 1}]$. Note that the degrees of the terms occurring in F, H_1, H_2 depend only on the coefficients of the linear system (which are bounded in terms of l) whereas the coefficients of F, H_1, H_2 depend only on the linear system and on the point P_0 , both of which are fixed in the present discussion.

Since $f^{\mathbf{u}} = g(h_1^{\mathbf{u}}/h_2^{\mathbf{u}})$ holds for all $\mathbf{u} \in \mathbb{Z}^p$, we deduce that $F = g(H_1/H_2)$. But then H_1/H_2 is integral over the integrally closed ring $\mathbb{C}[z_1^{\pm 1}, \dots, z_p^{\pm 1}]$ and therefore $H_1/H_2 \in \mathbb{C}[z_1^{\pm 1}, \dots, z_p^{\pm 1}]$. Note now that $\deg(H_1/H_2) \leq \deg H_1 + \deg H_2$. Hence the number of terms of the Laurent polynomial H_1/H_2 is bounded by $(1 + 2 \deg H_1 + 2 \deg H_2)^p$. But $p, \deg H_1, \deg H_2$ depend only on the linear system, and are therefore bounded only in terms of l.

This also shows that the number of terms of $h^{\mathbf{u}}(x) = h_1^{\mathbf{u}}(x)/h_2^{\mathbf{u}}(x)$ is bounded by a function only of l, and the same holds for $\mathbf{u} = \mathbf{u}_0$, proving Theorem 1.

Finally, Theorem 2* is obtained from Theorem 1 just by repeating the opening arguments of this proof; we have only to forget about $h_1(x), h_2(x)$ and keep only h(x), which, as we now know, has at most $B_3(l)$ terms.

Proof of Theorem 2. Theorem 2 is a mere rephrasing of Theorem 2*. In fact, by construction, starting from the variety \mathcal{V}_j of Theorem 2* we may obtain F_j, G_j, H_j as in Theorem 2, just by setting $z_i := x^{u_i}$ and by taking the coefficients to be the coordinate functions on \mathcal{V}_j .

⁽³⁾ Note also that a priori one equation $f = g \circ h$ may give points and solutions in more than one way; this is because certain equalities between degrees do not exclude further equalities.

⁽⁴⁾ It may be easily seen that the non-negative solutions of an integral linear system may be parametrized as linear combinations with non-negative coefficients of a finite system of generators.

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